



9

Associators

How to relate objects to each other

Create relations

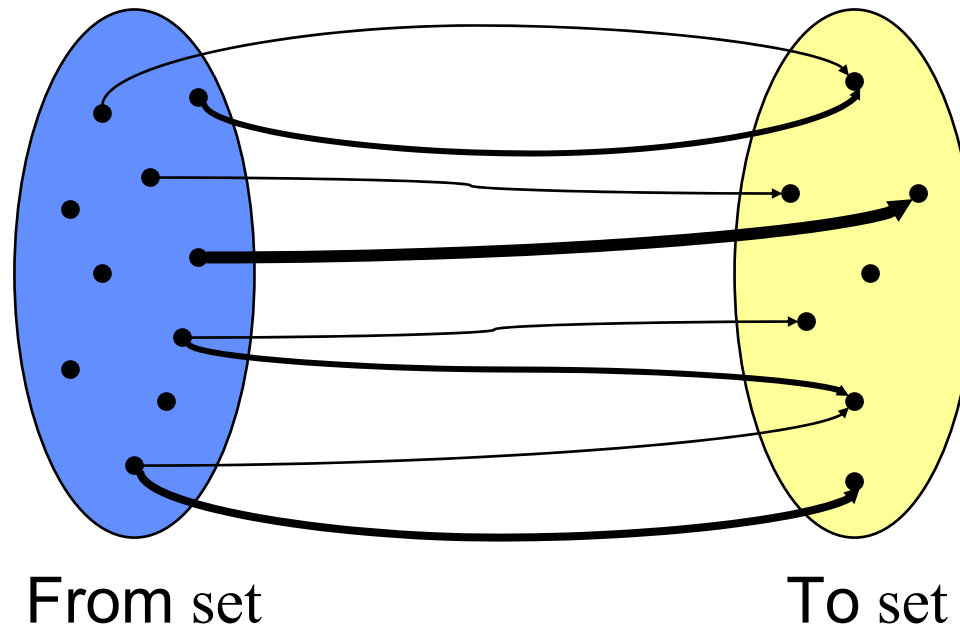
Save relations

Use relations: Associators



Relations between objects

- **Which type of objects**
 - Any object: int, double, complex class, keyed/contained objects...
 - Most interesting: two sets of contained objects
- **What is a relation?**



Types of relations

- **One or two directional (1D / 2D)**
 - But reverse relations can always be retrieved from direct relations
 - Hence, only 1D relations are made persistent
 - Advice: create only 1D relations, unless both usages are frequent
- **Normal relations**
 - Simple link between objects
 - Not necessarily between all objects of each set
 - Possibly several links from/to an object
- **Weighted relations**
 - The link carries additional information (can be any class)
 - An ordering should be possible on the *WEIGHT* class
 - Example: int, double
 - But could be complex class with the == and < operators defined



How to create relations

1. Instantiate the relation table (in the creation algorithm)

```
#include "MyAssociator.h"
```

```
.....
```

```
new Table* table; // The type "Table" is defined in MyAssociator.h
```

2. Usually one loops on all objects in the FROM set

```
for( from_iterator frlt=from.begin(); from.end()!=frlt; frlt++) {
```

3. For each object, decide which objects of the TO set to link to, possibly which weight.

```
double weight = computeWeight( frlt, tolt );
```

```
if( weight > 0 ) { // Example of how to decide
```

4. Establish the relation

```
table->relate( *frlt, *tol [ , weight]);
```



How to save relations (1)

- **Once the table is filled**
- **Optionally apply filters (if weighted)**
 - FromObj* from;
 - ToObj* to;
 - Weight threshold;
 - table->filterFrom(from, threshold, {false,true});
 - // Keeps only relations with weight > (true) or > than a threshold
- **Optionally remove some relations (all)**
 - table->removeFrom(from);
 - table->removeTo(to);



How to save relations (2)

- **Declare the relations table in the transient store**
 StatusCode sc =
 eventSvc()->registerObject(outputData(), table);
 // outputData() returns the location in TES
 // it should be declared as a property of the algorithm
- **If the table should be discarded (e.g. in case of error)**
 - **Do not forget to**
 delete table; // avoid memory leaks!



How to use relations?

- In order to use relations, the user algorithm should use a Gaudi tool called an Associator
- Generic Associator tool available
- Guidelines for Associators
 - Specialise the associator (for ease of use)
 - New class derived from the **class Associator**
 - For weighted Associators: **class AssociatorWeighted**
- Where does the tool look for the table?
 - The tool looks in the TES
 - If not found, it tries and get it from the PES
 - If not found, one can define a construction algorithm which should save the relations table in the TES (at the location they are expected!)



Associators

- Naming conventions

- Type of the Associator tool

```
class FromObj2ToObjOtherInfoAsct : public  
    Associator[Weighted]<FromObj,ToObj[,Weight]> { . . . };
```

OtherInfo is optional (should not reflect the method used but the content)

- If ToObj and FromObj can be “factorised”, do not repeat the common part in ToObj

```
class Particle2MCWeightedAsct;  
class ITCluster2MCParticleAsct;
```

- Type for the relations table

```
FromObj2ToObjOtherInfoAsct::Table
```

- Type for the Associator tool interface

```
FromObj2ToObjOtherInfoAsct::IAsct
```



Declaring an associator

- In **MyAssociator.h** (note that “Weighted” is only in case of weighted relations)

```
#include "Relations/AssociatorWeighted.h"
. . . .
class Particle2MCWeightedAsct :
  public AssociatorWeighted<Particle,MCParticle,double>
{
public:
  // Define data types
  // Define the relations table, templated class
  typedef RelationWeighted1D<Particle,MCParticle,double> Table;
  // Defines the type of the base associator
  typedef OwnType          Asct;
. . . .
// Minimal constructor
  Particle2MCWeightedAsct(const std::string& type, const std::string& name,
                          const IInterface* parent )
    : Asct( type, name, parent) { };
}
```



Declaring an associator (2)

- **Declare types for retrieving ranges of objects**
 - When getting objects related to a given From (To) object, one gets a “range”
 - A “range” can be seen as a list/vector of objects
 - A “range” has an iterator, with the usual begin() and end() methods
 - For ease of use, one can define meaning full types for ranges, e.g.

```
typedef Particle2MCWeightedAsct::FromRange    ParticlesToMC;  
typedef Particle2MCWeightedAsct::FromIterator ParticlesToMCIterator;  
typedef Particle2MCWeightedAsct::ToRange      MCsFromParticle;  
typedef Particle2MCWeightedAsct::ToIterator   MCsFromParticleIterator;
```

- **DLL file for loading the tool**
 - `MyAssociators_dll.cpp`

```
#include "GaudiKernel/LoadFactoryEntries.h"  
LOAD_FACTORY_ENTRIES(PhysAssociators)
```



Declaring an Associator (3)

- A `_load.cpp` file must be defined to declare the necessary factories

- `MyAssociators_load.cpp`:

```
#include "DaVinciAssociators/Particle2MCWeightedAsct.h"
// Declare factory for the associator
DECLARE_TOOL_FACTORY( Particle2MCWeightedAsct );
// Declare factory for the relations table
DECLARE_OBJECT_FACTORY( Particle2MCWeightedTable );
..
DECLARE_FACTORY_ENTRIES( PhysAssociators ) {
    DECLARE_OBJECT( Particle2MCWeightedTable ); // Declare the Table object
    DECLARE_TOOL( Particle2MCWeightedAsct ); // Declare the Associator tool
    DECLARE_ALGORITHM( Particle2MCWeighted ); // Declare the construction algorithm
}
```



Retrieving an Associator

- **An instance of the tool should be created in the user algorithm**

- **Returns a pointer to an Associator interface (type Iasct*):**

```
Particle2MCWeightedAsct::IAsct* m_pAsctWithChi2; ///< Pointer to associator with chi2  
as weight
```

```
.....
```

```
// This is the Particle2MCWeighted tool
```

```
sc = toolSvc()->retrieveTool( "Particle2MCWeightedAsct",  
                             m_pAsctWithChi2); ["MyAssociator",]
```

```
/// "Particle2MCWeightedAsct" is the type of the tool (as in _load)
```

```
/// m_pAsctWithChi2 is a pointer to the interface used later on
```

```
/// ["MyAssociator",] is an optional private name to that tool
```



Using an Associator

- Retrieve a range of ToObj given a FromObj

```
Particle* part = ...;
```

```
...
```

```
MCsfromParticle mcParts = m_pAsctWithChi2->rangeFrom( part );
```

```
MCsfromParticleIterator mcPartIt;
```

```
for( mcPartIt = mcParts.begin(); mcParts.end() != mcPartIt; mcPartIt++) {
```

```
...
```

```
// CAUTION: *mcPartIt is not of type MParticle!!!
```

```
MParticle* mcPart = mcPartIt->to();
```

```
Weight weight = mcPartIt->weight();
```

```
}
```

- Similarly one can retrieve a range of FromObj given a ToObj

```
Particle* part = ...;
```

```
...
```

```
ParticlesToMC parts = m_pAsctWithChi2->rangeTo( mcPart );
```



Using an Associator (2)

- Often, relations are one-to-one between the two sets
 - Possibly no linked object, but never 2 or more
 - Shortcut to directly access the object:

```
MCParticle* mcPartChi2;  
double chi2;  
mcPartChi2 = m_pAsctWithChi2->associatedFrom( *part[, chi2]);  
if( mcPartChi2 ) {  
    // There was an associated MCParticle  
} else {  
    // There was no associated MCParticle OR there was not relations table  
}
```



Using an Associator (3)

- **Advanced usage of weighted associators**

- One can retrieve relations which have a weight larger (smaller) than a threshold

```
Particle* part = . . . ;
```

```
. . .
```

```
MCsfromParticleChi2 mcParts =
```

```
    m_pAsctWithChi2->rangeWithHighCutFrom( part, maxChi2 );
```

```
// This will return a range containing only associated MCParticles
```

```
// if the weight (i.e. the chi2) is smaller than maxChi2
```

- **No one-to-one retrieval method with cut, but trivially**

```
double chi2;
```

```
mcPartChi2 = m_pAsctWithChi2->associatedFrom( *part, chi2);
```

```
if( mcPartChi2 && chi2 < maxChi2) {
```

```
    // There was an associated MCParticle with chi2 < maxChi2
```

```
}
```



Using an Associator (4)

- **Miscellaneous features**

- **Testing if the relations table is present**

```
if( false == m_pAsctChi2->tableExists() ) {  
    // The table doesn't exist  
} else {  
    // One can retrieve information safely  
}
```

- **Getting a status code when retrieving a range**

```
Range range;  
StatusCode sc = m_pAsct->rangeFrom( from, range);  
if( sc.isSuccess() ) {  
    // One can use range safely  
}
```



JobOptions for Associators

- **Properties of the base class**

- **No default: to be defined in the constructor using**

- `set_property(name, value);`

- **Location of the relations table in the TES**

- `Toolsvc.Particle2MCWithChi2Asct.Location = "Phys/Relations/Particle2MCWithChi2";`

- **Convention for the location name:**

- **Root: the TES branch of the “To” objects**
 - **/Relations**
 - **Leaf: name of the Associator**

- **Creation algorithm**

- `ToolSvc.Particle2MCWithChi2Asct.AlgorithmType = "Particle2MCWithChi2";`

- `ToolSvc.Particle2MCWithChi2Asct.AlgorithmName = "Particle2MCWithChi2";`

- **Note: one can give an alternate name to the Associator and/or to the algorithm... The same Associator can be used twice with different settings**



JobOptions for Associators (2)

- **Example of dual usage of a single associator**

- **In the code, retrieve the same tool with two different names**

```
// First the WithChi2 associator (of type Particle2MCWeightedAsct)
sc = toolSvc()->retrieveTool( "Particle2MCWeightedAsct", "WithChi2Asct", m_pAsctWithChi2);
// This is another type of Particle2MC tool, differentiated by jobOptions
sc = toolSvc()->retrieveTool("Particle2MCWeightedAsct", "LinkAsct", m_pAsctLinks);
```

- **In the JobOptions file, declare different locations and algorithms**

```
// first associator using chi2 as weight
Toolsvc.WithChi2Asct.Location    = "Phys/Relations/Particle2MCWithChi2";
ToolSvc.WithChi2Asct.AlgorithmType = "Particle2MCWithChi2";
ToolSvc.WithChi2Asct.AlgorithmName = "Particle2MCWithChi2";
// alternate associator using stored links
Toolsvc.LinkAsct.Location    = "Phys/Relations/Particle2MCLinks";
ToolSvc.LinkAsct.AlgorithmType = "Particle2MCLinks";
ToolSvc.LinkAsct.AlgorithmName = "Particle2MCLinks";
```



Further features

- **Location of the table**

- **Advise:**

- **Use as for containers a static const definition in the .h file**

- ```
static const std::string& Particle2MCAstLocation = "Phys/Relations/Particle2MC";
```

- **Define the Associator property (in the Associator constructor)**

- ```
setProperty( location, Particle2MCAstLocation );
```

- **Use for registering in the TES *OutputTable* as property of the algorithm**

- ```
declareProperty("OutputTable", m_outputTable = Particle2MCAstLocation);
```

- ```
...
```

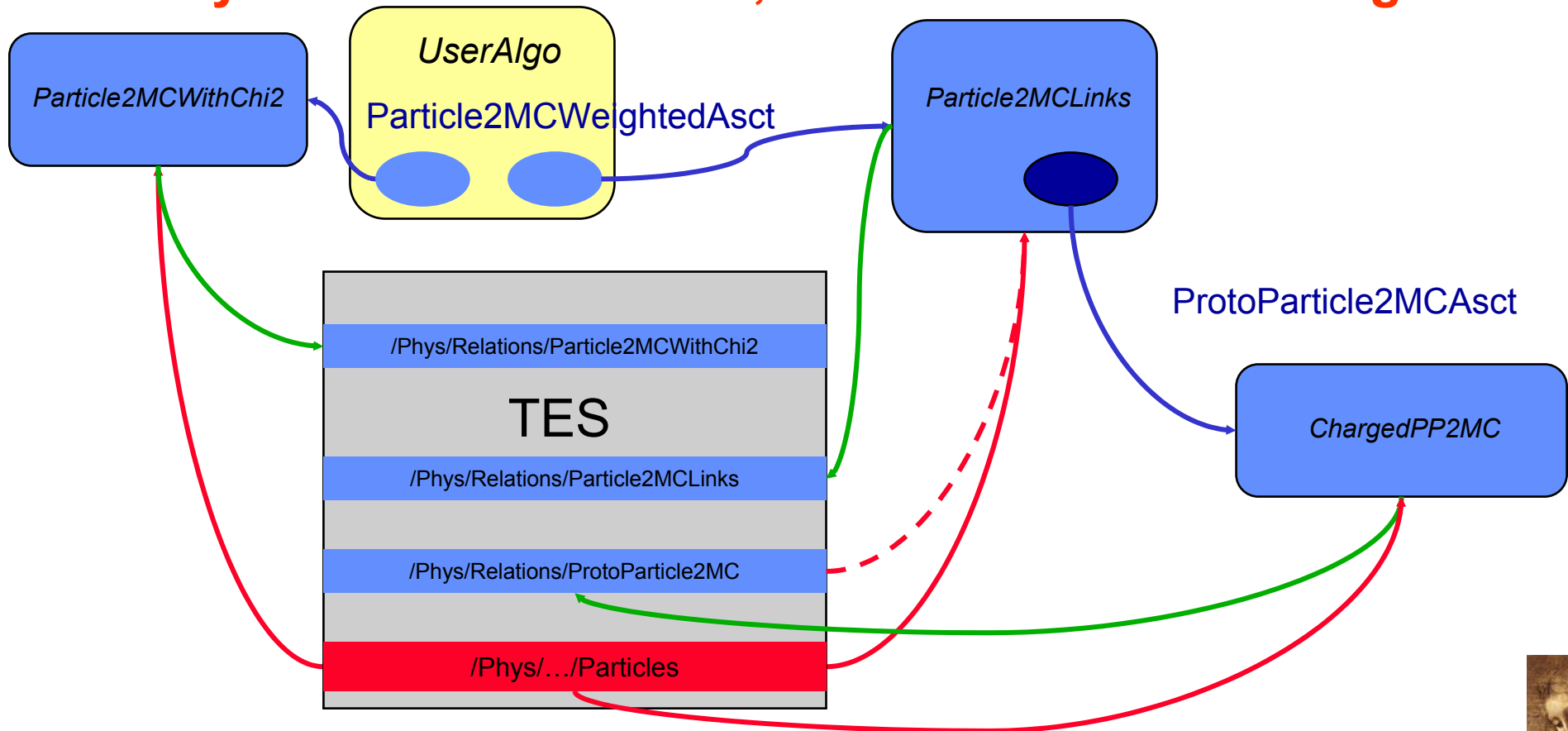
- ```
StatusCode sc = eventSvc()->registerObject(outputTable(), table);
```

- **The associator automatically sets the *OutputTable* property of the algorithm**



# DaVinci Associators

- Package Phys/DaVinciAssociators
- Many associators defined, with various creation algorithms



# DaVinciAssociators 2

- **Algorithm properties**

- **Particle2MCWithChi2.opts**

- Particle2MCWithChi2.InputData = {"Phys/Production/Particles"};

- Particle2MCWithChi2.OutputTable = "Phys/Relations/Particle2MCWithChi2";

- Particle2MCWithChi2.FillHistos = true;

- **Particle2MCChi2.opts**

- Particle2MCChi2.InputData = {"Phys/Production/Particles"};

- Particle2MCChi2.OutputTable = "Phys/Relations/Particle2MC";

- Particle2MCChi2.Chi2Cut = 100.;

- **Particle2MCLinks.opts**

- Particle2MCLinks.InputData = {"Phys/Production/Particles"};

- Particle2MCLinks.OutputTable = "Phys/Relations/Particle2MCLinks";



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# Summary

- **Associators and relations tables are very powerful means for linking indirectly objects**
  - No explicit link in the data model
  - Relations are external and can be serialized or re-created
  - **Exemples:**
    - Particle to MCParticle
    - Clusters to MCParticle
    - Vertex to Particles (not implemented that way, but could be)
- **A generic tool exists, could be used as such**
- **For physics studies, we suggest to follow guidelines described in this presentation**
- **Other users could follow them as well...**

